## PHYSICS 2DL - SPRING 2010

## MODERN PHYSICS LABORATORY

Monday April 19, 2010

Prof. Brian Keating

* UCSD


## Homework

- Problems listed on 2DL Spring 2010 -Web Site.
- All HW problems are found in Taylor
- Hand-in HW to TA in Lab


## Averaging Data

- Random Errors can be reduced by repeated measurements.
- The best estimate of the true value of a measured quantity is the average (mean).

$$
\bar{x}=\frac{1}{n}_{i=1}^{n}
$$

- We can also estimate the RMS $\left.\sigma_{x}^{2}=\frac{1}{n-1}{ }_{i=1}^{n}\left(x_{i}-\bar{x}\right)^{2}\right)$
$\underline{\text { error from the set of }}$ measurements.
- We can then compute the error on the mean which decreases with the number of measurements.
$\sigma_{\bar{x}}=\frac{\sigma_{x}}{\sqrt{n}}$

If $\sigma_{x}$ is 1 mm , how many times must I measure to get a 0.2 mm

## Example of Error Propagation

Suppose that $q=x+y+z$. We wish to determine $q$ by measuring $x, y$, and $z$. The error on $q,(\delta q)$, can be calculated from the errors on the measured quantities.
$q=x+y+z$
$\delta q=\delta x+\delta y+\delta z$ If $\delta x$ is an error estimate, we don't know its sign.
$\delta q=|\delta x /+|\delta y|+|\delta z| \quad$ Worst case, if all have same sign.
$\sigma_{q}=\sqrt{(\delta x)^{2}+(\delta y)^{2}+(\delta z)^{2}} \quad$ Independent, random errors.
$\sigma=R M S=$ standard deviation

## Another Example of Error Propagation

$$
\begin{array}{ll}
q=x y \quad \begin{array}{l}
\text { Definition (area): assume the correct values are } x, y \text { and } \\
q, \text { but, we measure }(x+\delta x) \text { and }(y+\delta y) . \text { We will then compute } \\
\\
(q+\delta q) \text { from our measurements. }
\end{array}
\end{array}
$$

$$
q+\delta q=(x+\delta x)(y+\delta y)=x y+x \delta y+y \delta x \quad \text { compute }
$$

$\delta q=x \delta y+y \delta x=\frac{\partial q}{\partial v} \delta y+\frac{\partial q}{\partial x} \delta x \quad$ Subtract $\boldsymbol{q}$ from both sides of the above equation and neglect $\delta x \delta y$. Notice partial derivatives.

In estimating the errors, we don't know the sign of $\delta x$ and $\delta y$.
Sometimes the error contributions will cancel, sometimes add.
We can compute errors two ways:
${ }^{\bullet}$ maximum possible error $\quad \delta q=\left|\frac{\partial q}{\partial x} \delta x\right|+\left|\frac{\partial q}{\partial y} \delta y\right|$
-RMS error

## Root Mean Square (RMS) Errors

$$
\delta q=\frac{\partial q}{\partial y} \delta y+\frac{\partial q}{\partial x} \delta x
$$

Compute error on $q(x, y)$ from errors one $x$ and $y$. This assumes you actually know the sign and magnitude of the errors.
Define root mean square error estimate

$$
\begin{array}{cl}
\sigma_{x} \equiv \sqrt{\left\langle\left(x_{\text {meas. }}-x_{\text {true }}\right)^{2}\right\rangle} & \begin{array}{l}
\text { Average over many } \\
\text { measurements. }
\end{array} \\
\sigma_{q}=\sqrt{\left(\frac{\partial q}{\partial x} \sigma_{x}^{2}+\left(\frac{\partial q}{\partial y} \sigma_{y}\right.\right.} \quad \begin{array}{l}
\text { Propagation of errors using } \\
\text { the RMS. We will mainlv }
\end{array} \\
\sigma=\left(\begin{array}{l}
\text { use this method. }
\end{array}\right. \\
\begin{array}{ll}
\text { What do we do when the } \\
\text { partial derivative is negative? }
\end{array} &
\end{array}
$$

## Why Use Partial Derivatives

1) It worked for the $q=x y$ case.
2) It makes sense graphically.

3) Its really the first order Taylor expansion of a function. $f(x, y, z)=f\left(x_{0}, y_{0}, z_{0}\right)+\left.\frac{\partial f}{\partial x}\right|_{x_{0}, y_{0}, z_{0}}\left(x-x_{0}\right)+\left.\frac{\partial f}{\partial y}\right|_{x_{0}, y_{0}, z_{0}}\left(y-y_{0}\right)+\left.\frac{\partial f}{\partial z}\right|_{x_{0}, y_{0}, z_{0}}\left(z-z_{0}\right)+\ldots$

## Fractional Errors are Sometimes Useful

For products like $q=x y$, we can add the fractional errors on the measurements to get the fractional error on the result.

$$
\begin{aligned}
& \frac{\sigma_{q}}{q}=\sqrt{{\sqrt{{\frac{\sigma_{x}}{x}}^{2}}+\left({\frac{\sigma_{y}}{y}}^{2}\right.}^{\sigma_{q}=\sqrt{\left(\frac{\partial q}{\partial x} \sigma_{x}\right.}+\left(\frac{\partial q}{\partial y} \sigma_{y}\right.}}
\end{aligned}
$$

Simple Derivation

$$
\frac{\sigma_{q}}{q}=\frac{1}{x y} \sqrt{\left(y \sigma_{x}\right)^{2}+\left(x \sigma_{y}\right)^{2}}=\sqrt{\left(\frac{\sigma_{x}}{x}\right)^{2}+\left(\frac{\sigma_{y}}{y}\right)^{2}}
$$

This also works for quotients like $q=\frac{x}{y}$

$$
\text { For } V=\frac{4}{3} \pi r^{3} \text {, the fractional error is } \frac{\sigma_{V}}{V}=\frac{1}{V} \frac{\partial V}{\partial r} \sigma_{r}=\frac{4 \pi r^{2}}{\frac{4}{-\pi r^{3}}} \sigma_{r}=3 \frac{\sigma_{r}}{r}
$$

## Example of Error Propagation

Find the fractional error on $q(x, y)=\frac{x^{n}}{y}$
$\sigma_{q}=\sqrt{\left(\frac{\partial q}{\partial x} \sigma_{x}{ }^{2}+\left(\frac{\partial q}{\partial y} \sigma_{y}\right.\right.}{ }^{2} \quad$ Our basic formula.
$\frac{\sigma_{q}}{q}=\frac{y}{x^{n}} \sqrt{\left(\frac{n x^{n-1}}{y} \sigma_{x}\right.}{ }^{2}+\left(-{\frac{x^{n}}{y^{2}} \sigma_{y}}^{2}=\sqrt{\left(n{\frac{\sigma_{x}}{x}}^{2}+\left(\frac{\sigma_{y}}{y}\right.\right.}{ }^{2}\right.$

This is the technique you'll need to memorize and use often.



## Probability Distributions

- Assume the true value of $x$ is 5.5 m . We make repeated measurements of $x$ with an "error" of 2.5 m .
- What do we expect the distribution of measurements to look like? This depends on the probability distribution.
- This is one possible example.

What is the probability to measure $\boldsymbol{x}=5$ ?


What is the probability to measure $x$ between 6 and 10 ?

## 0

Can you think of something with a flat probability distribution? 10







Limiting distribution


## Standard Normal (Gaussian) Distribution



- Many probability distributions, including errors, approach the Normal distribution.
- Biological parameters
- Test scores
- Any combination of random variables (Central Limit Theorem).
- Normal distribution has average and standard deviation as parameters.


## The Normal Distribution



- $X$ and $\sigma$ are parameters of the Normal distribution.
- $X$ is the true mean of the distribution.
- The RMS width of the distribution is $\sigma$.

What are the units of $P(x)$ ?

- $x$ is the independent variable.
- $\boldsymbol{P}$ is the probability density to measure $\boldsymbol{x}$.




| $t=1$ | Table A. The percentage probability, $\operatorname{Prob}($ within $t \sigma)=\int_{X-t \sigma}^{X+t \sigma} G_{X, \sigma}(x) d x$, as a function of $t$. |  |  |  |  |  | $x-$ |  | X | $X+t o$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | (t) | 0.00 | 0.01 | 0.02 | 0.03 | 0.04 | 0.05 | 0.06 | 0.07 | 0.08 | 0.09 |  |
|  | 40 | 0.00 | 0.80 | 1.60 | 2.39 | 3.19 | 3.99 | 4.78 | 5.58 | 6.38 | 7.17 |  |
|  | d 1 | 7.97 | 8.76 | 9.55 | 10.34 | 11.13 | 11.92 | 12.71 | 13.50 | 14.28 | 15.07 |  |
|  | ${ }^{2}$ | 15.85 | 16.63 | 17.41 | 18.19 | 18.97 | 19.74 | 20.51 | 21.28 | 22.05 | 22.82 |  |
|  | d. 3 | 23.58 | 24.34 | 25.10 | 25.86 | 26.61 | 27.37 | 28.12 | 28.86 | 29.61 | 30.35 |  |
|  | ¢ 4 | 31.08 | 31.82 | 32.55 | 33.28 | 34.01 | 34.73 | 35.45 | 36.16 | 36.88 | 37.59 |  |
|  | d 5 | 38.29 | 38.99 | 39.69 | 40.39 | 41.08 | 41.77 | 42.45 | 43.13 | 43.81 | 44.48 |  |
|  | ( 6 | 45.15 | 45.81 | 46.47 | 47.13 | 47.78 | 48.43 | 49.07 | 49.71 | 50.35 | 50.98 |  |
|  | ¢. 7 | 51.61 | 52.23 | 52.85 | 53.46 | 54.07 | 54.67 | 55.27 | 55.87 | 56.46 | 57.05 |  |
|  | ¢ 8 | 57.63 | 58.21 | 58.78 | 59.35 | 59.91 | 60.47 | 61.02 | 61.57 | 62.11 | 62.65 |  |
|  | d9 | 63.19 | 63.72 | 64.24 | 64.76 | 65.28 | 65.79 | 66.29 | 66.80 | 67.29 | 67.78 |  |
|  |  | 68.27) | 68.75 | 69.23 | 69.70 | 70.17 | 70.63 | 71.09 | 71.54 | 71.99 | 72.43 |  |
|  | 1.1 | 72.87 | 73.30 | 73.73 | 74.15 | 74.57 | 74.99 | 75.40 | 75.80 | 76.20 | 76.60 |  |
|  | 1.2 | 76.99 | 77.37 | 77.75 | 78.13 | 78.50 | 78.87 | 79.23 | 79.59 | 79.95 | 80.29 |  |
|  | 1.3 | 80.64 | 80.98 | 81.32 | 81.65 | 81.98 | 82.30 | 82.62 | 82.93 | 83.24 | 83.55 |  |
|  | 1.4 | 83.85 | 84.15 | 84.44 | 84.73 | 85.01 | 85.29 | 85.57 | 85.84 | 86.11 | 86.38 |  |
|  | 1.5 | 86.64 | 86.90 | 87.15 | 87.40 | 87.64 | 87.89 | 88.12 | 88.36 | 88.59 | 88.82 |  |
|  | 1.6 | 89.04 | 89.26 | 89.48 | 89.69 | 89.90 | 90.11 | 90.31 | 90.51 | 90.70 | 90.90 |  |
|  | 1.7 | 91.09 | 91.27 | 91.46 | 91.64 | 91.81 | 91.99 | 92.16 | 92.33 | 92.49 | 92.65 |  |
|  | 1.8 | 92.81 | 92.97 | 93.12 | 93.28 | 93.42 | 93.57 | 93.71 | 93.85 | 93.99 | 94.12 |  |
|  | 1.9 | 94.26 | 94.39 | 94.51 | 94.64 | 94.76 | 94.88 | 95.00 | 95.12 | 95.23 | 95.34 |  |
|  | 2.0 | 95.45 | 95.56 | 95.66 | 95.76 | 95.86 | 95.96 | 96.06 | 96.15 | 96.25 | 96.34 |  |
|  | 2.1 | 96.43 | 96.51 | 96.60 | 96.68 | 96.76 | 96.84 | 96.92 | 97.00 | 97.07 | 97.15 |  |
|  | 2.2 | 97.22 | 97.29 | 97.36 | 97.43 | 97.49 | 97.56 | 97.62 | 97.68 | 97.74 | 97.80 |  |
|  | 2.3 | 97.86 | 97.91 | 97.97 | 98.02 | 98.07 | 98.12 | 98.17 | 98.22 | 98.27 | 98.32 |  |
|  | 2.4 | 98.36 | 98.40 | 98.45 | 98.49 | 98.53 | 98.57 | 98.61 | 98.65 | 98.69 | 98.72 |  |
|  | 2.5 | 98.76 | 98.79 | 98.83 | 98.86 | 98.89 | 98.92 | 98.95 | 98.98 | 99.01 | 99.04 |  |
|  | 2.6 | 99.07 | 99.09 | 99.12 | 99.15 | 99.17 | 99.20 | 99.22 | 99.24 | 99.26 | 99.29 | 5 |
|  | 2.7 | 99.31 | 99.33 | 99.35 | 99.37 | 99.39 | 99.40 | 99.42 | 99.44 | 99.46 | 99.47 |  |
|  | 2.8 | 99.49 | 99.50 | 99.52 | 99.53 | 99.55 | 99.56 | 99.58 | 99.59 | 99.60 | 99.61 |  |



## Limiting Distributions; Normal Distribution (Ch.5)

Plan:
-Limiting distributions: physical meaning
-Normal (Gauss) distribution
-Addition in quadrature, SDOM, etc










- Accepted Value of $\mathrm{h}=6.626 \times 10^{-34} \mathrm{~J}$.sec
- You measure freq $=45 \mathrm{THz}$ with uncertainty:
- $\mathrm{dF}=4.5 \mathrm{THz}$
- What is best estimate for the Uncertainty in Energy $=\mathrm{hF}$ ?
- $E=3.0 \pm 0.3 \times 10^{-20} \mathrm{~J}$



$\mathrm{W}_{80} \mathrm{~W}-1(\mu \mathrm{~W} / \mathrm{W})$


FIG. 3. The daily average of the latest watt results. The error Fars. are the standard deviation of the mean each day's results.

FIG. 2. Histogram of most recent 989 watt measurements.

| Uncertainty source | Value ( $\mathrm{nW} / \mathrm{w}$ ) |  |
| :---: | :---: | :---: |
| Reference transfers (type B) |  |  |
| $\xrightarrow{\text { Mass }}$ Resistance | 20 |  |
| Vesistance | ${ }_{30}$ |  |
| Length | 5 |  |
| Frequency | 5 |  |
| Gravity | 7 |  |
| External effects |  |  |
| Mass buoyancy | 23 |  |
| Alignments | 40 |  |
| Leakage resistance | 20 |  |
| Magnetic fux $z$-profile fit | 20 |  |
| Knife-edge hysteresis RF noise offsets | 20 10 |  |
| RSS subtotal | 82 | 39 |
| Statistical type A | 30 87 |  |



Fitting Voltage Data to $\mathrm{V}=\mathrm{IR}$

$$
\begin{aligned}
& \frac{\partial \chi^{2}}{\partial R}=0 \\
& \text { IMPLIES : } \\
& R=\frac{\sum_{i}^{N} I_{i} V_{i}}{\sum_{i}^{N} I^{2}{ }_{i}}
\end{aligned}
$$

$\mathrm{N}=$ number of data points. In this
example, $N=4$

What is the Error on the Best-Fit Parameter R?
Our general formula, which always applies, is:

$$
\sigma_{R}=\sqrt{\left(\frac{\partial R}{\partial V_{1}}\right)^{2} \sigma_{\eta_{1}}^{2}+\left(\frac{\partial R}{\partial V_{2}}\right)^{2} \sigma_{v_{2}}^{2}+\ldots\left(\frac{\partial R}{\partial V_{N}}\right)^{2} \sigma_{v_{N}}^{2}}
$$

Since: $\quad\left(\frac{\partial R}{\partial V_{1}}\right)^{2}=I_{1}^{2},\left(\frac{\partial R}{\partial V_{N}}\right)^{2}=I_{N}^{2}$

$$
\text { and }: \sigma_{V_{V}}=1 \mathrm{mV}
$$




